

## Model Predictive Control: Theory, Computation, and Design 2nd Edition

### Errata for Second Edition, First Printing

Check [www.che.wisc.edu/~jbrow/mpc](http://www.che.wisc.edu/~jbrow/mpc) for a current list

December 7, 2017

1. p. 114, Assumption 2.14 (a). Change  $\ell(x, u)r$  to  $\ell(x, u)$  in the last inequality.
2. p. 329, Exercise 4.7, 3rd line. Change, “let  $y(\cdot)$  be any  $\mathcal{K}$  function,” to “let  $y(\cdot)$  be any  $\mathcal{K}$  function and  $a_i \in \mathbb{R}_{\geq 0}, i \in \mathbb{1}_{1:n}$ .”